

INTEL EMBEDDED SYSTEMS COMPETITION 2016

More info about software and hardware compatible with Intel® Galileo Gen 2

In this webinar

- Getting started
 - Hardware revision
 - Communicating to the board
 - Firmware update
- Operating Systems Highlights
 - Yocto project based image
 - Debian
 - FreeRTOS
 - Zephyr
 - Wind River* Rocket* / Linux
 - Ostro



In this webinar

- Building a custom kernel
 - Yocto Project
 - Ostro
- Software Highlights
 - Intel XDK IoT Edition
 - Intel System Studio IoT Edition
- General Information
- Q&A



Intel[®] Galileo Gen 2 – Hardware Revision





Communicating to the board

- USB through Arduino IDE
 - Compile sketches and run Linux commands using the exclusive system() function (e.g. system("ifconfig > /dev/ttyGSO");)
- SSH through Ethernet cable or WiFi connection and PuTTY
 - Full access to terminal
 - Require SSH enabled
- SERIAL through FTDI/USB cable
 - Full access to terminal
 - Great for testing and debugging an image
 - Do not require ssh connection



System() – why you should be careful

- Since sketch task is initiated at boot is important to notice the outcome of shell command parsed as a string on System() function
- One **really bad** use is System("shutdown –h now"); Please don't do it 🙂
- In case you did this or something similar, in which you can not rewrite /sketch/sketch.elf file with a new sketch, follow these instructions.
 - Remove the sdcard and plug it in to a Linux host (VM is ok)
 - Find the sketch folder and remove sketch.elf file
 - Eject sd card and insert back in Galileo
 - You now should be able to boot properly



Firmware Update – option 1

- Update from 1.0.2 to 1.0.4 using the provided tool by Intel
- Download software and tutorial <u>https://downloadcenter.intel.com/download/24748/Intel-Galileo-Firmware-and-Drivers-1-0-4</u>
- Useful tips:
 - Don't run the program with the sdCard connected
 - Run as administrator (sudo for Linux users)
 - Wait for the board fully boot and be recognized before running the software
 - Make sure you selected the right port



Firmware Update – option 2

- Update from 1.0.2 to 1.0.4 using a **specific** version of Arduino IDE
- Download software <u>https://downloadcenter.intel.com/download/24782/Intel-Arduino-1-5-3</u>
- Open IDE and go to Help -> Galileo Firmware Update
- Useful tips:
 - Unzip into C:/ directory using 7-zip tool
 - Don't run the program with the sdCard connected
 - Wait for the board fully boot and be recognized
 - Make sure you selected the right board and port
 - If Arduino IDE does not open please consider the following solution <u>http://forum.arduino.cc/index.php?topic=234307.0</u>



Yocto Project – prebuilt image

Download EGLIBC image
<u>https://software.intel.com/en-us/iot/hardware/galileo/downloads</u>

http://downloadmirror.intel.com/25384/eng/iot-devkit-201510010757mmcblkp0-galileo.direct.xz

- Unzip with 7zip
- Burn .img or .direct file to micro sdCard (Win32DiskImager or using dd command)

Login: root **no password required**

- Arduino* IDE support
- Development tools C/C++, Python*, Node.js* and OpenJDK 1.8



Debian

- Download image <u>https://sourceforge.net/projects/galileodebian/files/SD%20card%20Image/</u>
- Unzip with 7zip
- Burn .img file to micro sdCard
- Login: root Password: root

Resources:

- Familiar Linux environment
- Access to Debian package repository and software updates
- Access to preconfigure Debian packages (e.g. Nano)



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Ostro

- Getting started guide <u>https://ostroproject.org/documentation/quick_start/quick_start.html</u>
- Pre-built images <u>https://download.ostroproject.org/</u>

- OS tailored for IoT smart devices and built with security in mind
- Base OS image can be used as-is or rebuilt (similar structure to Yocto Project)
- Support for Node.js* , Python* 2.7, C/C++ and Java* (preconfigured in ostroimage-swupd-dev-intel-quark)

FreeRTOS

- Download image and full tutorial <u>http://www.freertos.org/RTOS_Intel_Quark_Galileo_GCC.html</u>
- Prebuilt examples

Login: root Password: intel

- Provides a predictable (deterministic) execution pattern
- Allows user to assign a priority to each thread of execution (task)
- Provides the core real time scheduling functionality, inter-task communication and timing



Zephyr

- Getting started and building demo for Galileo
- Getting started <u>https://www.zephyrproject.org/doc/getting_started/getting_started.html#getting-started</u>
- Linux install <u>https://www.zephyrproject.org/doc/getting_started/installation_linux.html</u>
- Galileo + Zephyr <u>https://www.zephyrproject.org/doc/board/galileo.html</u>
- Application Development <u>https://www.zephyrproject.org/doc/application/apps_dev_process.html</u>
- Prebuilt examples

- Real-Time Operating System (RTOS) for IoT
- Small, scalable and modular
- Developed with security in mind
- Offers a microkernel and a nanokernel



Wind River* Rocket*

- Getting started guide <u>https://software.intel.com/sites/default/files/managed/b0/51/Wind_River_R</u> <u>ocket_GETTING_STARTED_GUIDE.pdf</u>
- Free embedded RTOS for IoT

- Kernel based on Zephyr microkernel
- Code and debug applications from any browser
- Cloud-based development environment
- Development in C
- Arduino* API
- Require serial connection (FTDI cable)



Wind River* Linux*

Initial setup

https://software.intel.com/sites/default/files/managed/b0/51/Wind_River_R ocket_GETTING_STARTED_GUIDE.pdf

 Access your account on Wind River[®]Helix[™]App Cloud, select New Device -> Create a new device from the supported SDK -> follow the provided instructions

- Code and debug applications from any browser
- Cloud-based development environment
- Development in C/C++ and Node.js*
- Require internet access and be on the same network with cloud workspace



Building a custom kernel

Why one might want to compile a custom kernel?

- $\checkmark\,$ Gain more control over the embedded application
- ✓ Performance compile only what's necessary
- ✓ Better use of resources reduce overhead
- ✓ Knowledge Learn more about the kernel



Building a custom kernel – Yocto Project (1)

- BSP 1.2.1
- Tutorial and needed files <u>https://downloadcenter.intel.com/download/23197/Intel-Quark-BSP?product=79084</u>
- Offers:
 - Prebuilt Python* 2.7
 - Easy connection to wireless networks with connmanctl
 - Kernel version 3.14.28
 - Opkg package manager
- Built and validated on Debian 7 and 8



Building a custom kernel – Yocto Project (2)

- Devkit Daisy 1.6.1
- Tutorial <u>http://www.embarcados.com.br/galileo-yocto/</u>
- Offers:
 - Support to Python* 2.7, Node.js* and Arduino* IDE
 - MRAA and UPM libraries
 - Easy connection to wireless networks with connmanctl
 - Kernel version 3.8.7

• Built and validated on Ubuntu 12.04 and Debian 7 and 8



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Building a custom kernel – Ostro

- Tutorial <u>https://ostroproject.org/documentation/howtos/building-images.html#building-images</u>
- Based on Yocto Project
- Offers:
 - Support to GCC, Python* 2.7, Node.js* and OpenJDK 1.8
 - Easy connection to wireless networks with connmanctl
 - Kernel version 4.4.9

• Built and validated on Debian 7 and 8



"We should forget about small efficiencies, say about 97% of the time: premature optimization is the root of all evil."

—Donald Knuth

Making Embedded Systems by Elecia White - O'Reilly, 2011

Intel® System Studio IoT Edition

- Plugin for Eclipse* that allows to connect to, update, and program IoT projects on a compatible board
- C/C++ and Java

Tips:

- For Windows* users it may help have installed MinGW (with all basic tools)
- Requires Java* JDK 1.8+, if Eclipse* does not automatically find it, please consider the following: Window -> Preferences -> Java -> Installed JREs -> Add -> Standard VM -> JRE Home (set path to jdk1.8_x) -> Finish -> unselect jre8 -> Ok



Intel[®] XDK IoT Edition

- IDE for JavaScript* and Node.js* programming
- User guide <u>https://software.intel.com/en-us/getting-started-with-the-intel-xdk-iot-edition</u>

- Enables easy on-board app development and deployment
- Deploy, run and debug in the same place
- Provides quick start templates and samples
- Integrates with cloud, web services, and sensors through JavaScript APIs
- HTML5 app creation



Intel® Galileo (Gen 2) – Network Connectivity

- While the Galileo board doesn't come with Wi-Fi connectivity, you can add to it.
- Any Linux-supported Wi-Fi card should work.
- Both wired and wireless connectivity settings can also be managed through the connmanct1 tool.

 Link for Intel Centrino drivers <u>https://wireless.wiki.kernel.org/en/users/</u> <u>Drivers/iwlwifi</u>





Configuring Package Repository – Intel Galileo

- OPKG is the package manager of Yocto images (usage e.g. opkg install nodejs-npm)
- To update the paths, please consider the following guide:

In **/etc/opkg** we are going to edit *iotdk.conf* and *mraa-upm.conf*

For iotdk.conf:

src iotdk-i586 <u>http://iotdk.intel.com/repos/3.0/iotdk/i586/</u> src iotdk-intel-core-2-32 <u>http://iotdk.intel.com/repos/3.0/iotdk/intel_core2_32/</u> src iotdk-quark <u>http://iotdk.intel.com/repos/3.0/iotdk/quark/</u> src iotdk-x86 <u>http://iotdk.intel.com/repos/3.0/iotdk/x86/</u> src iotdk-core-2-32 <u>http://iotdk.intel.com/repos/3.0/iotdk/core2-32/</u>

For mraa-upm.conf:

src mraa-upm http://iotdk.intel.com/repos/3.0/intelgalactic/opkg/i586/



Intel[®] Galileo and Embedded Systems– Useful books

- Embedded Linux Development with Yocto Project by Otavio Salvador; Daiane Angolini – Packt, 2014
- Intel[®] Galileo and Intel[®] Galileo Gen 2: API Features and Arduino Projects for Linux Programmers by Manoel Carlos Ramon – Apress, 2015
- Internet of Things with Intel Galileo by Miguel de Sousa Packt, 2015
- Node.js for Embedded Systems by Patrick Mulder; Kelsey Breseman O'Reilly, 2016 (early release)



Intel[®] Galileo – Useful links

- Galileo downloads: <u>https://software.intel.com/en-us/iot/hardware/galileo/downloads</u>
- Galileo IDE downloads: <u>https://software.intel.com/en-us/iot/software/ide</u>
- Yocto Project Development Manual: <u>http://www.yoctoproject.org/docs/current/dev-manual/dev-manual.html</u>
- Videos Competition Intel Embedded Systems 2015: <u>https://www.youtube.com/playlist?list=PLdv8QZ_rwBOdwKX-LVTrv62MQfYiJ2XTk</u>
- Our website:

http://sbesc.lisha.ufsc.br/sbesc2016/Intel+Embedded+Systems+Competition

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Don't forget...

- Keep your schedule up-to-date weekly
- Got a question? Ask us!

submissaocompeticaointel@gmail.com

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Next Webinar...

- August 23 15h00
- August 24 10h30

Next Deadline...

 September 20 – Partial Report Submission (through JEMS)



