



INTEL EMBEDDED SYSTEMS COMPETITION 2016

More info about software and hardware compatible with Intel® Galileo Gen 2

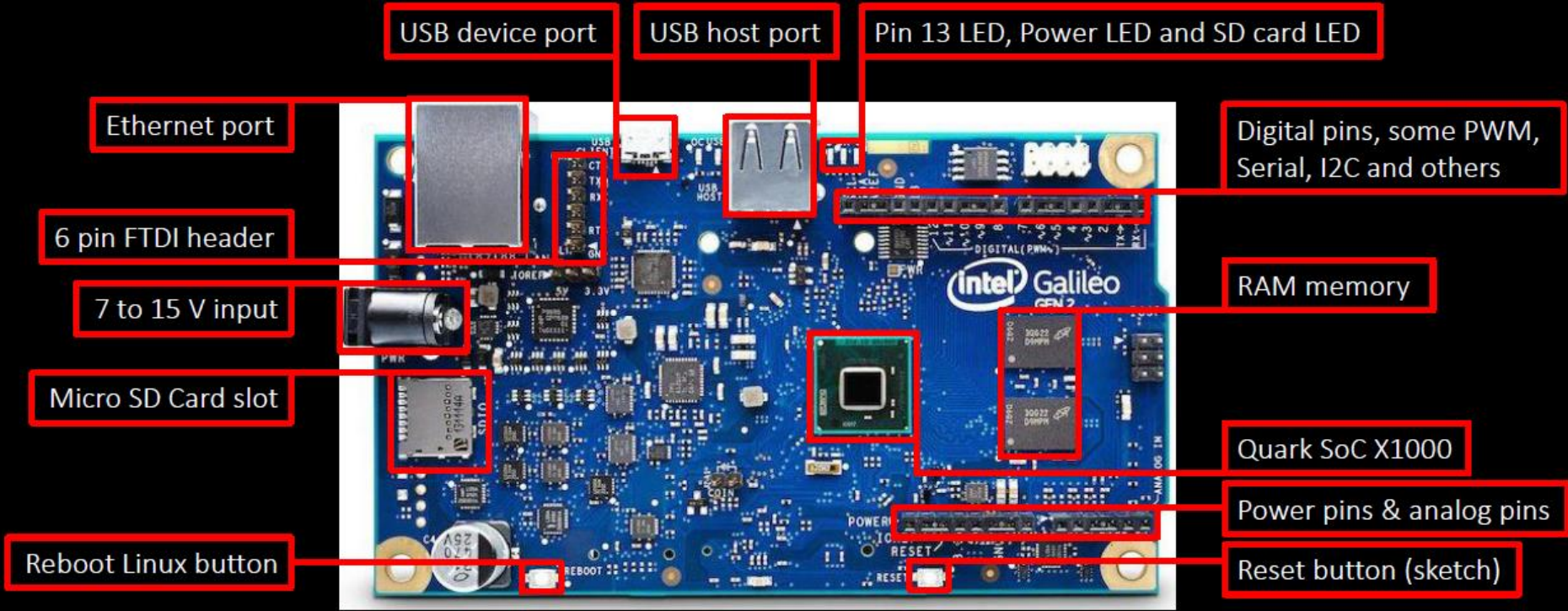
In this webinar

- Getting started
 - Hardware revision
 - Communicating to the board
 - Firmware update
- Operating Systems Highlights
 - Yocto project based image
 - Debian
 - FreeRTOS
 - Zephyr
 - Wind River* Rocket* / Linux
 - Ostro

In this webinar

- Building a custom kernel
 - Yocto Project
 - Ostro
- Software Highlights
 - Intel XDK IoT Edition
 - Intel System Studio IoT Edition
- General Information
- Q&A

Intel® Galileo Gen 2 – Hardware Revision



Communicating to the board

- USB – through Arduino IDE
 - Compile sketches and run Linux commands using the exclusive `system()` function (e.g. `system("ifconfig > /dev/ttyGSO");`)
- SSH – through Ethernet cable or WiFi connection and PuTTY
 - Full access to terminal
 - Require SSH enabled
- SERIAL – through FTDI/USB cable
 - Full access to terminal
 - Great for testing and debugging an image
 - Do not require ssh connection

System() – why you should be careful

- Since sketch task is initiated at boot is important to notice the outcome of shell command parsed as a string on System() function
- One **really bad** use is System(“shutdown –h now”); Please don't do it 😊
- In case you did this or something similar, in which you can not rewrite /sketch/sketch.elf file with a new sketch, follow these instructions.
 - Remove the sdcard and plug it in to a Linux host (VM is ok)
 - Find the sketch folder and remove sketch.elf file
 - Eject sd card and insert back in Galileo
 - You now should be able to boot properly

Firmware Update – option 1

- Update from 1.0.2 to 1.0.4 using the provided tool by Intel
- Download software and tutorial
<https://downloadcenter.intel.com/download/24748/Intel-Galileo-Firmware-and-Drivers-1-0-4>
- Useful tips:
 - Don't run the program with the sdCard connected
 - Run as administrator (sudo for Linux users)
 - Wait for the board fully boot and be recognized before running the software
 - Make sure you selected the right port

Firmware Update – option 2

- Update from 1.0.2 to 1.0.4 using a **specific** version of Arduino IDE
- Download software
<https://downloadcenter.intel.com/download/24782/Intel-Arduino-1-5-3>
- Open IDE and go to Help -> Galileo Firmware Update
- Useful tips:
 - Unzip into **C:/** directory using 7-zip tool
 - Don't run the program with the sdCard connected
 - Wait for the board fully boot and be recognized
 - Make sure you selected the right board and port
 - If Arduino IDE does not open please consider the following solution
<http://forum.arduino.cc/index.php?topic=234307.0>

Yocto Project – prebuilt image

- Download EGLIBC image

<https://software.intel.com/en-us/iot/hardware/galileo/downloads>

<http://downloadmirror.intel.com/25384/eng/iot-devkit-201510010757-mmcb1kp0-galileo.direct.xz>

- Unzip with 7zip
- Burn .img or .direct file to micro sdCard (Win32DiskImager or using dd command)

Login: root **no password required**

Resources:

- Arduino* IDE support
- Development tools C/C++, Python*, Node.js* and OpenJDK 1.8

Debian

- Download image
<https://sourceforge.net/projects/galileodebian/files/SD%20card%20Image/>
- Unzip with 7zip
- Burn .img file to micro sdCard

Login: root Password: root

Resources:

- Familiar Linux environment
- Access to Debian package repository and software updates
- Access to preconfigure Debian packages (e.g. Nano)

Ostro

- Getting started guide

https://ostroproject.org/documentation/quick_start/quick_start.html

- Pre-built images

<https://download.ostroproject.org/>

Resources:

- OS tailored for IoT smart devices and built with security in mind
- Base OS image can be used as-is or rebuilt (similar structure to Yocto Project)
- Support for Node.js* , Python* 2.7, C/C++ and Java* (preconfigured in ostro-image-swupd-dev-intel-quark)

FreeRTOS

- Download image and full tutorial
http://www.freertos.org/RTOS_Intel_Quark_Galileo_GCC.html
- Prebuilt examples

Login: root Password: intel

Resources:

- Provides a predictable (deterministic) execution pattern
- Allows user to assign a priority to each thread of execution (task)
- Provides the core real time scheduling functionality, inter-task communication and timing

Zephyr

- Getting started and building demo for Galileo
- ❖ Getting started https://www.zephyrproject.org/doc/getting_started/getting_started.html#getting-started
- ❖ Linux install https://www.zephyrproject.org/doc/getting_started/installation_linux.html
- ❖ Galileo + Zephyr <https://www.zephyrproject.org/doc/board/galileo.html>
- ❖ Application Development https://www.zephyrproject.org/doc/application/apps_dev_process.html
- Prebuilt examples

Resources:

- Real-Time Operating System (RTOS) for IoT
- Small, scalable and modular
- Developed with security in mind
- Offers a microkernel and a nanokernel

Wind River* Rocket*

- Getting started guide
https://software.intel.com/sites/default/files/managed/b0/51/Wind_River_Rocket_GETTING_STARTED_GUIDE.pdf
- Free embedded RTOS for IoT

Resources:

- Kernel based on Zephyr microkernel
- Code and debug applications from any browser
- Cloud-based development environment
- Development in C
- Arduino* API
- Require serial connection (FTDI cable)

Wind River* Linux*

- Initial setup
https://software.intel.com/sites/default/files/managed/b0/51/Wind_River_Rocket_GETTING_STARTED_GUIDE.pdf
- Access your account on Wind River® Helix™ App Cloud, select New Device -> Create a new device from the supported SDK -> follow the provided instructions

Resources:

- Code and debug applications from any browser
- Cloud-based development environment
- Development in C/C++ and Node.js*
- Require internet access and be on the same network with cloud workspace

Building a custom kernel

Why one might want to compile a custom kernel?

- ✓ Gain more control over the embedded application
- ✓ Performance – compile only what's necessary
- ✓ Better use of resources – reduce overhead
- ✓ Knowledge - Learn more about the kernel

Building a custom kernel – Yocto Project (1)

- BSP 1.2.1
- Tutorial and needed files
<https://downloadcenter.intel.com/download/23197/Intel-Quark-BSP?product=79084>
- Offers:
 - Prebuilt Python* 2.7
 - Easy connection to wireless networks with connmanctl
 - Kernel version 3.14.28
 - Opkg package manager
- Built and validated on Debian 7 and 8

Building a custom kernel – Yocto Project (2)

- Devkit Daisy 1.6.1
- Tutorial <http://www.embarcados.com.br/galileo-yocto/>
- Offers:
 - Support to Python* 2.7, Node.js* and Arduino* IDE
 - MRAA and UPM libraries
 - Easy connection to wireless networks with connmanctl
 - Kernel version 3.8.7
- Built and validated on Ubuntu 12.04 and Debian 7 and 8

Building a custom kernel – Ostro

- Tutorial
<https://ostroproject.org/documentation/howtos/building-images.html#building-images>
- Based on Yocto Project
- Offers:
 - Support to GCC, Python* 2.7, Node.js* and OpenJDK 1.8
 - Easy connection to wireless networks with connmanctl
 - Kernel version 4.4.9
- Built and validated on Debian 7 and 8

“We should forget about small efficiencies, say about 97% of the time: premature optimization is the root of all evil.”

—Donald Knuth

Making Embedded Systems by Elecia White – O’Reilly, 2011

Intel® System Studio IoT Edition

- Plugin for Eclipse* that allows to connect to, update, and program IoT projects on a compatible board
- C/C++ and Java

Tips:

- For Windows* users it may help have installed MinGW (with all basic tools)
- Requires Java* JDK 1.8+, if Eclipse* does not automatically find it, please consider the following: Window -> Preferences -> Java -> Installed JREs -> Add -> Standard VM -> JRE Home (set path to jdk1.8_x) -> Finish -> unselect jre8 -> Ok

Intel® XDK IoT Edition

- IDE for JavaScript* and Node.js* programming
- User guide
<https://software.intel.com/en-us/getting-started-with-the-intel-xdk-iot-edition>

Resources:

- Enables easy on-board app development and deployment
- Deploy, run and debug in the same place
- Provides quick start templates and samples
- Integrates with cloud, web services, and sensors through JavaScript APIs
- HTML5 app creation

Intel® Galileo (Gen 2) – Network Connectivity

- While the Galileo board doesn't come with Wi-Fi connectivity, you can add to it.
- Any Linux-supported Wi-Fi card should work.
- Both wired and wireless connectivity settings can also be managed through the `connmanctl` tool.
- Link for Intel Centrino drivers
<https://wireless.wiki.kernel.org/en/users/Drivers/iwlwifi>



Configuring Package Repository – Intel Galileo

- OPKG is the package manager of Yocto images (usage e.g. `opkg install nodejs-npm`)
- To update the paths, please consider the following guide:

In **`/etc/opkg`** we are going to edit *`iotdk.conf`* and *`mraa-upm.conf`*

For `iotdk.conf`:

```
src iotdk-i586 http://iotdk.intel.com/repos/3.0/iotdk/i586/  
src iotdk-intel-core-2-32 http://iotdk.intel.com/repos/3.0/iotdk/intel\_core2\_32/  
src iotdk-quark http://iotdk.intel.com/repos/3.0/iotdk/quark/  
src iotdk-x86 http://iotdk.intel.com/repos/3.0/iotdk/x86/  
src iotdk-core-2-32 http://iotdk.intel.com/repos/3.0/iotdk/core2-32/
```

For `mraa-upm.conf`:

```
src mraa-upm http://iotdk.intel.com/repos/3.0/intelgalactic/opkg/i586/
```


Intel® Galileo and Embedded Systems– Useful books

- Embedded Linux Development with Yocto Project by Otavio Salvador; Daiane Angolini – Packt, 2014
- Intel® Galileo and Intel® Galileo Gen 2: API Features and Arduino Projects for Linux Programmers by Manoel Carlos Ramon – Apress, 2015
- Internet of Things with Intel Galileo by Miguel de Sousa – Packt, 2015
- Node.js for Embedded Systems by Patrick Mulder; Kelsey Breseman – O'Reilly, 2016 (early release)

Intel® Galileo – Useful links

- Galileo downloads:
<https://software.intel.com/en-us/iot/hardware/galileo/downloads>
- Galileo IDE downloads: <https://software.intel.com/en-us/iot/software/ide>
- Yocto Project Development Manual:
<http://www.yoctoproject.org/docs/current/dev-manual/dev-manual.html>
- Videos Competition - Intel Embedded Systems 2015:
https://www.youtube.com/playlist?list=PLdv8QZ_rwBOdwKX-LVTrv62MQfYiJ2XTk
- Our website:
<http://sbesc.lisha.ufsc.br/sbesc2016/Intel+Embedded+Systems+Competition>

Don't forget...

- Keep your schedule up-to-date weekly
- Got a question? Ask us!

submissaocompeticaointel@gmail.com

Next Webinar...

- August 23 – 15h00
- August 24 – 10h30

Next Deadline...

- September 20 – Partial Report Submission
(through JEMS)

